

Contents

FOREWORD BY L. A. DuBRIDGE	vii
PREFACE.	ix

PART I. INTRODUCTION

CHAP. 1. PRINCIPLES OF RADAR.	3
HOW RADAR WORKS.	3
1-1. The Fundamental Ideas	3
1-2. Resolution, Accuracy, and Coverage.	10
1-3. Design Considerations.	15
PROPAGATION.	21
1-4. Curvature of the Earth and Atmospheric Refraction.	21
1-5. Atmospheric Attenuation	22
INDICATORS.	26
1-6. Cathode-ray Tubes	26
1-7. Synchros, Servomechanisms, and Amplidynes.	28
1-8. Different Types of Indicators.	30
RADAR BEACONS	36
1-9. Operation	36
1-10. Future Developments; Systems.	41
CHAP. 2. NONRADAR NAVIGATIONAL METHODS	44
2-1. Nonradar Navigational Methods	44
2-2. Radio Ranges	44
2-3. German Radio Range, Sonne.	47
2-4. Ultra-high-frequency, Navigational Aids, uhf.	50
2-5. Airborne and Shipborne Direction Finders	51
2-6. Ground Direction Finders	54
2-7. Celestial Navigation.	55
LORAN AND OTHER NAVIGATIONAL NETS	56
2-8. Hyperbolic Systems.	56
2-9. Gee.	60
2-10. Loran	64
2-11. "SS" Loran	70
2-12. Low-frequency Loran	72
2-13. Decca,	76

2-14. Accuracy and Range of Various Hyperbolic Systems.	77
2-15. Automatic Data Analysis	79
2-16. Automatic Piloting	82

PART II. AIRBORNE RADAR

CHAP. 3. CHARACTERISTICS OF AIRBORNE RADAR.	89
INTRODUCTION	89
3-1. Features Revealed by Radar Mapping.	89
3-2. Details in Radar Mapping	96
3-3. The Operator.	105
3-4. Measurement of Drift and Ground Speed	105
3-5. Determination of Drift and "Ground Speed" Over Water	110
3-6. Information Available on Flights Over Water.	112
3-7. The Use of Maps as Aids to Radar Pilotage	115
3-8. Radar Beacon Navigation	117
CHAP. 4. SPECIAL AIDS AND DEVICES.	122
NAVIGATION AND ANTICOLLISION	122
4-1. The Ground Position Indicator.	122
4-2. Anticollision Radar Devices	128
ALTITUDE DETERMINATION.	131
4-3. Pulsed Radio Altimeters (SCR-718C)	132
4-4. Frequency-modulated Altimeters (AN/APN-1).	136
4-5. Comparison of F-m and Pulsed Altimeters.	141
4-6. Suggested Future Trends.	142
CHAP. 5. SPECIAL DESIGN CONSIDERATIONS.	143
5-1. Receivers	143
5-2. Indicators	148
5-3. Antennas	155
5-4. Antenna Stabilization	156
CHAP. 6. ENGINEERING AND ECONOMIC CONSIDERATIONS.	161
6-1. Installation.	161
6-2. General Design Considerations	165
6-3. Performance of AN/APS-10	171
6-4. Characteristics of the AN/APS-10 Radar: I	174
6-5. Characteristics of the AN/APS-10 Radar: II.	181
6-6. Typical Performance of Some Existing Systems.	185
6-7. Economic Aspects of Airborne Radar	187

PART III. GROUND-BASED RADAR

CHAP. 7. TYPES OF GROUND-BASED RADAR AND SPECIAL EQUIP- MENT.	193
SEARCH AND AUTOMATIC-TRACKING RADARS.	193
7-1. A Long-range Microwave System.	193
7-2. Automatic Tracking Systems.	202

HEIGHT FINDERS	207
7-3. Height-finding Methods	207
7-4. General Problems of Design	212
7-5. Illustrations of Some Recent Systems	218
RADAR AIDS FOR LANDING	227
7-6. Beam Approach Systems	227
7-7. Beacon Approach Systems, BABS	232
7-8. Ground-based Scanning Radar Systems	237
SPECIAL RADAR AIDS	252
7-9. Moving Target Indication	252
7-10. Beacons	256
7-11. Radar Relay	258
7-12. Video Mapping	267
7-13. Radar Aids to Mapping	278
CHAP. 8. RADAR AIDS TO AIR NAVIGATION AND TRAFFIC CONTROL	285
8-1. Statement of the Problem	285
8-2. Navigation and Traffic Control Using Airborne Radar Aids	293
8-3. Navigation and Traffic Control Using Ground-based Radar Aids	299
8-4. Summary of Proposed Aids	311
 PART IV. SHIPBORNE RADAR 	
CHAP. 9. NAVIGATION AND PILOTAGE	317
9-1. How Radar Can Help the Navigator	317
9-2. Coordination of Radar Data with Other Data	320
9-3. Marine Radar Beacons	322
9-4. Corner Reflectors	324
9-5. Principle of Superposition Navigation	331
9-6. Chart-matching Equipment	335
9-7. Accuracy Obtainable by Chart Matching	344
9-8. PPI Simulations	351
BIBLIOGRAPHY	353
CHAP. 10. A SHIPBORNE NAVIGATIONAL RADAR	354
10-1. Radar Propagation over Water	354
10-2. General Specifications of a Shipborne Navigational Radar	363
10-3. Antenna Assembly	364
10-4. Transmitter-receiver Package	371
10-5. Indicator	373
10-6. Power Supply	377
10-7. Physical Characteristics of the Components and Test Equipment	379
INDEX	383